STUDIES ON SINGLE AND TWIN PRIME MOVER TRAVELLING WAVE THERMOACOUSTIC SYSTEMS

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Abstract— Experimental and Simulation studies on single prime mover travelling wave thermoacoustic system have been performed for various working fluids such as Argon, Helium etc. at different operating pressures. Then simulation study on twin prime mover travelling wave thermoacoustic system is performed using DeltaEC software where resonators, regenerators, cold heat exchangers, ambient heat exchangers and stack ducts are modeled. The system performance is studied at various operating pressures for various working fluids such as pure gases and binary mixture of helium and Argon. The newly modeled twin prime mover system has better performance in terms of pressure amplitude and resonance frequency when compared to that of a single prime mover travelling wave system. The studies on Helium/Argon mixtures in various proportions as a working fluid in twin prime mover travelling wave system are performed. The helium/Argon mixture at 60/40 ratio proves to be more efficient as its Prandtl number is less. The pressure amplitude of 0.1224 Mpa and frequency of 30 Hz at 1 Mpa operating pressure is recorded at He/Ar 60/40 ratio mixture.

Keyword - DeltaEC, Heat engines, multistage prime movers, Prime movers, Thermoacoustics.

I. INTRODUCTION

Thermoacoustic prime movers are of two types, namely standing wave and travelling wave. It is evident from the previous studies and the available literature that travelling wave prime movers performance is better. A single prime mover traveling wave thermoacoustic system is developed and studied in detail. An effort is made to model a twin type (two prime movers in series) travelling wave thermoacoustic prime mover using the DeltaEC modeling software. From the parameter study, such as pressure amplitude and frequency, suitable dimensions for various components are arrived. Then the behavior of the developed model is studied for different operating pressures.

In the year 2011, B. Yu et al. experimentally studied, travelling wave thermoacoustic refrigeration driven by thermoacoustic prime mover, with single prime mover system the operating frequency of 57 Hz and 3 Mpa pressure could be achieved. In 2013, Bharatbhushan V Kamble et al. studied the performance of twin standing wave thermoacoustic prime mover for pulse tube refrigeration. The work included both experimental as well as the simulation using DeltaEC software and the results were in good match. In the year 2013, N.M. Hariharan et al. studied the effect of resonator length and working fluid on the twin standing wave prime mover. The experimental results were compared with the results of DeltaEC simulation software. M Chen et al. in the year 2013 developed a small scale travelling wave thermoacoustic heat engine with operating frequency of 45 Hz and with charge pressure of 0.53 Mpa. Shinya Hasegawa et al. in the year 2013 developed multistage thermoacoustic engine to drive thermoacoustic refrigerator. In this the temperature required for the engine is considerably less, due to multiple stages. In 2014, Dong-Hui Li et al. developed liquid piston travelling wave thermoacoustic heat engine and studied the behavior with different working fluids. Mathew Skaria et al. developed simulation models for standing wave and travelling wave thermoacoustic prime movers using DeltaEC simulation software and CFD simulation software, the results were matched. Jingvuan Xu et al. designed and developed double acting thermoacoustic heat engine with operating pressure of 4 Mpa and 300 Hz as working frequency for thermoacoustic refrigerator. M Chen et al. in the year 2015 studied the effect of working gases on the small thermoacoustic sterling engine. The experimental results were validated with the simulated results of DeltaEc.

II. STUDIES ON SINGLE PRIME MOVER SYSTEM

The experimental set up of the Single prime mover system is as shown in Fig 1. The system consists of two parts, a feedback loop and resonator with the buffer. Heater, ambient heat exchanger, stack (made of stainless steel wire mesh), cold heat exchanger, and the compliance tubes are housed in the feedback loop. The heater provides heat energy required to the hot heat exchanger and the cold heat exchanger is circulated with ambient water that can take heat from the other end of the stack. This creates a temperature gradient across the stack, which generates thermoacoustic oscillations. The traveling wave loop is attached with a resonator tube along with the buffer.

To understand the behaviour, the developed travelling wave thermoacoustic prime mover is experimented and performance of the same is studied for various working fluids. The system with similar configuration is modelled using DeltaEC software, the results are compared.

Fig 2 shows resonance frequency of the system measured with different working fluid at different operating pressures. The resonance frequency of the traveling wave system depends on the working fluid. The resonance frequency is independent of operating pressure for a working fluid. As the frequency of oscillation for traveling wave thermoacoustic prime mover is directly proportional to the speed of sound in particular working gas. It is expressed as, "f=a/4L", where 'a' is speed of sound and is given by, $a = \sqrt{(\gamma(P/\rho))}$. γ is the ratio of specific heats, P is the pressure, ρ is the density of working fluid.



Fig 1. Travelling wave thermoacoustic single prime mover experimental setup.

Increasing the operating pressure correspondingly increases the density of the working gas in the system. So the ratio of working pressure and density remains nearly constant. Hence, the frequency of oscillation is nearly constant with the increase in working pressure. Also Helium shows highest frequency, since the density of gas within the constant volume varies according to the molecular weight. The molecular weight of Helium is low and Argon is high.



Fig 2. Experimental and simulated frequencies as function of operating pressure.

Fig 3 shows experimental and simulated pressure amplitude as function operating pressure for Helium and Argon. The pressure amplitude is directly proportional to the operating pressure. This can be attributed as, according to linear thermoacoustics (Swift, 1988) the momentum, continuity and energy equations the pressure amplitude is directly proportional to velocity amplitude by the inertance and viscous resistance. Both inertance and viscous resistance of working gas depend upon the mean density of working gas in the system.

As the operating pressure of the working gas in the system is increased, the density increases correspondingly which leads to the increase in pressure amplitude. Also it is observed that, the pressure amplitude is the highest for Argon, the lowest for Helium. This is because the pressure amplitudes depend on the density of the working gas, and as higher the molecular weight, higher the density causes highest pressure amplitude for Argon as working gas and lowest for Helium due to its lowest density.

Argon shows the highest pressure amplitude at the lowest frequency of ~ 23 Hz at an average pressure of 0.51 MPa. On the other hand, Helium shows the lowest pressure amplitude at the highest frequency of ~ 73 Hz. The reasons for the variation of pressure amplitude with the working fluid have been already explained. The variation in frequency among the working fluids is due to the difference in their molecular weights, which modifies the sound velocity of the fluid.



Fig 3. Experimental and simulated pressure amplitudes as function of operating pressure.

III. DESIGN CONSIDERATIONS FOR MODELLING OF TWIN PRIME MOVER SYSTEM

- A tube of 50mm inner diameter and 57mm outer diameter is used for the modelling of the system.
- Initially DeltaEC program is developed for single prime mover system and later extended to desired twin prime mover layout.
- For the purpose of design of independent component, the operating pressure of 10 Mpa is set, with pure Argon as the working fluid.
- Necessary parameters such as porosity of heat exchangers, regenerators, thickness of ducts, length of feedback loop, outline of loops etc. are initially assumed suitably and then modified as per the requirements.
- All specifications such as porosity, radius, gap between the plates in case of heat exchangers, type of meshes in case of regenerators, heat input etc. is exactly similar in both the prime movers. To ensure generation of one single wave with single resonance frequency and pressure amplitude, absolute similarity between the prime movers is required.
- The two prime movers are arranged in series configuration.

IV. INITIAL PARAMETERS FOR MODELLING IN DELTAEC SOFTWARE

The following dimensions or specifications are initially used to develop the program of single prime mover system.

Parts name	Dimensions
Cold heat exchanger (one in numbers)	Length=75mm
	Porosity=0.66
	Tube Radius=2e-3m
Regenerator (one in numbers)	Length=45mm
	Porosity=0.66
	Hydraulic radius=1.12e-4m
Hot heat exchanger (one in numbers)	Length =70mm
	Porosity=0.66
	Half plate length=1e-3m
Ambient heat exchanger (one in	Length=45mm
numbers)	Porosity=0.66
	Tube Radius=2e-3m
Stack duct (one in numbers)	Length=100mm
	Wall Area=8.64e-4m^2
Resonator length	1 m

TABLE 1. Part Specifications for single prime mover

V. TWIN PRIME MOVER DESIGN



Fig 4. Design layout of twin prime mover system

A. Design of resonator tube

The resonator tube is the important component, by varying which both the resonance frequency as well as pressure amplitude varies. The resonator tube material is selected as stainless steel. The inner diameter of the resonator is taken as 50mm. The outer diameter is 57mm, with 3.5mm wall thickness. This decides cross sectional area of resonator through which fluid can flow. The Srough is inner surface roughness of the tube or duct, whose value is 6e-4 for turbulent dissipation of fluids. The appropriate length for the resonator has to be arrived. The variation of pressure amplitude and resonance frequency with the resonator length is plotted as shown in fig 4.

The pressure amplitude of the system increases almost linearly with resonator length and reaches maximum value of 0.1498 MPa at 2.6 m then the pressure amplitude decreases. The frequency decreases with increase in resonator length and at 2.6 m length its value is about 19.5 Hz. The Pressure amplitude has to be as high as possible with minimum resonance frequency for the best performance of the engine. Thus the resonator length of 2.6 m is arrived from the above graphs.



Fig 5. Pressure amplitudes and frequencies verses resonator length.

B. Design of cold heat exchangers

The cold heat exchangers are placed right below the regenerator. The working fluid moves inside small cylindrical holes of given porosity. It is made of copper, as it is a good conductor. There are two cold heat exchangers in twin prime mover system. A water jacket arrangement is made externally to circulate water at room temperature around the heat exchangers. The water pumping arrangements are made for continuous circulation of water. The diameter of the heat exchanger remains same as that of the inner diameter of the resonator tube; the length of the heat exchangers has to be determined. The graph shows the variation of pressure amplitude and frequency with heat exchanger length.



Fig 6. Pressure amplitudes and frequencies verses cold heat exchanger length.

The pressure amplitude increases with the length of cold heat exchanger, reaches a stable value at 0.055 m length and then drops. The frequency remains almost constant, with the order of 19-20 Hz. Thus the cold heat exchanger length is taken as 0.055 m.

C. Design of hot heat exchangers

This heat exchanger adds heat energy to the working fluid. The twin prime mover system has two hot heat exchangers made of copper. Heater of known power is used externally to supply heat energy. As the heat exchanger length increases, the heat transfer to the working fluid becomes better because of large area of contact, but the pressure amplitude decreases as it acts as the obstruction to the beginning of wave oscillation. So the

suitable length has to be selected such that the pressure amplitude is not too less and at the same time the operating temperature of the heat exchanger should be less than the melting point of the copper. The graph shows the variation of pressure amplitude and frequency with respect to the length of hot heat exchanger.



Fig 7. Pressure amplitudes and frequencies verses hot heat exchanger length.

Pressure amplitude decreases with length of hot heat exchanger up to 0.075 m. The frequency being 19-20 Hz remains almost constant with increase in length of hot heat exchanger. At 0.065 m length of the hot heat exchanger, pressure amplitude is about 0.1480 Mpa. The length of 0.065 m is an optimum value as the temperature remains well within the limit.

D. Design of ambient heat exchangers



Fig 8. Pressure amplitudes and frequencies verses ambient heat exchanger length.

Ambient heat exchangers are required to stabilize flow of the working fluid and to reduce the temperature of working fluid, thus preventing the temperature rise of the working fluid and the system. The two ambient heat exchangers are used in twin prime mover system. The graphs show the variation of pressure amplitude and frequency with length of ambient heat exchanger.

E. Design of regenerator

The twin prime-mover system contains two regenerators of wire mesh type. The regenerators are made of stainless steel mesh. As the length of the regenerator increases pressure amplitude increases and frequency remains constant. The temperature gradient is maintained across the regenerators.



Fig 9. Pressure amplitudes and frequencies verses regenerator length.

The regenerator is placed between cold and hot heat exchangers, whose lengths are 0.055 m and 0.065 m respectively. From the above graph, the appropriate length of regenerator is taken as 0.05 m. The other parameters are mesh type N=30, Porosity= 0.74, and hydraulic radius Rh=199.2e-6 m.

F. Design of stack duct

This duct decides the position of the prime movers and ambient heat exchangers. Increase in the length of this corresponds to increase in pressure amplitude and frequency remains almost constant. But the temperature of hot heat exchanger increases. The graphs show the variation of the amplitude and frequency with the length of stack.



Fig 10. Pressure amplitudes and frequencies verses stack duct length.

From the above graphs the appropriate value for the length of stack duct appears to be 0.1m. The wall area is $8.64e-4 \text{ m}^2$ corresponds to the wall thickness of 0.05 m.

V. DESIGN PARAMETERS ARRIVED FROM DELTAEC SOFTWARE

From DeltaEC software, specific design dimensions for twin prime mover system are arrived as shown.

Parts name	Dimensions
Cold heat exchanger (two in numbers)	Length=55mm
	Porosity=0.66
	Tube Radius=2e-3m
Regenerator (two in numbers)	Length=55mm
	Porosity=0.74
	Hydraulic radius=1.99e-4m
Hot heat exchanger (two in numbers)	Length =65mm
	Porosity=0.66
	Half plate length=1e-3m
Ambient heat exchanger (two in	Length=65mm
numbers)	Porosity=0.66
	Tube Radius=2e-3m
Stack duct (three in numbers)	Length=100mm
	Wall Area=8.64e-4m^2
Resonator length	2.6 m

TABLE II. Part Specifications for twin prime mover

VI.SIMULATION RESULTS OF TWIN PRIME MOVER SYSTEM

The Fig 11 and 12 show variation of resonance frequency and pressure amplitude with operating pressure respectively, for pure gases and binary mixtures of helium and Argon. The resonance frequency is independent of operating pressure. The pressure amplitude increases with operating pressure. The frequency of helium gas is higher than argon because of its low molecular weight.



Fig 11. Simulated results of resonance frequencies verses operating pressure.

The pressure amplitude of Argon is higher, as it has higher molecular weight than helium. From the above graphs, it is evident that the pressure amplitude is high for Argon with low resonance frequency, but the required temperature gradient across the regenerator for the beginning of the oscillation is very high. On other hand helium requires low temperature gradient to produces low pressure amplitude and high resonance frequency waves.



Fig 12. Simulated results of pressure amplitudes verses operating pressure.

A mixture of helium and argon in appropriate proportion will result in good pressure amplitude and frequency, operating at less temperature gradient when compared to pure gases. The pressure Amplitude and frequency of binary mixtures are plotted and it is evident from the graphs that the He/Ar mixture of 60/40 ration is optimum. The fluids with very low value of Prandtl number acts as best thermoacoustic fluid. The Prandtl number for He-Ar mixture of 60-40 ratio is least among all other mixtures thus acts as the best thermoacoustic working fluid. The same can be even visualized by simulation results.

VII. CONCLUSIONS

The Delta Ec modelling and simulation has been performed for single prime mover system, the results fairly matched with the experimental results. Then simulation study on twin prime mover system has been performed. The frequency of working fluid is almost independent of operating pressure. The pressure amplitude increases with operating pressure attains maximum value and then decreases. The DeltaEC successfully predicts the values of pressure amplitude and frequency, but fails to predict the T begin value. Among all the working fluids, binary mixture of He/Ar at 60/40 ratio acts as the best fluid due to its low Prandtl number, gives an intermediate optimum frequency and with considerably good pressure amplitude.

NOMENCLATURE

HX	Heat exchanger
HHX-1	Hot heat exchanger of first prime mover
CHX-1	Cold heat exchanger of first prime mover
STK-1	Regenerator of first prime mover
AHX-1	Ambient heat exchanger of first prime mover
HHX-2	Hot heat exchanger of second prime mover
CHX-2	Cold heat exchanger of second prime mover
STK-2	Regenerator of second prime mover
AHX-2	Ambient heat exchanger of second prime mover
Delta T1	Temperature gradient across regenerator-1
Delta T2	Temperature gradient across regenerator-2
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